



(V1.00)

.....		
.....		
1.1		- 3 -
1.2		- 3 -
1.3		- 3 -
1.4		- 3 -
1.5		- 3 -
1.6		- 3 -
1.7		- 3 -
1.8		- 3 -
1.9		- 3 -
.....		
.....		
2.1		8
2.2		8
2.3		- 3 -
2.4		- 3 -
2.5		- 3 -
2.6		- 3 -
2.7		- 3 -
2.8		- 3 -

$$U_{1m} \qquad \omega \qquad U_{R_1R_3}(t) = U_{1m} \, (\sin\omega t)$$

$$U_{S_1S_3}(t) = U_{2m} \, (\sin\omega t + \alpha) \, \cos(\theta)$$

2 1	0 1	f	W	

2 ¼ DB9

M

3 ¼ ǔ

ǔ

~

f

ĩ

4 ı ů	Ů ı	f ı	ĩ

